Quantum Weak Measurement and its Implementation in Optical Systems Independent Study

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2 The Math

- Optical Analog
- 4 Signal to Noise Ratio
- 5 Mixed Probe State

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An experiment proving quantized nature of intrinsic angular momentum

An experiment proving quantized nature of intrinsic angular momentum A beam of silver atoms passing through inhomogeneous transverse magnetic field An experiment proving quantized nature of intrinsic angular momentum A beam of silver atoms passing through inhomogeneous transverse magnetic field

For spin half particles, only two values of intrinsic angular momentum values are possible $\pm \hbar/2$

Stern-Gerlach Experiment



Figure: Classical expectation versus quantum result of the SG experiment

Weak Measurement?

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Strong measurement - Change in the state of the system and the measuring device $% \left({{{\left[{{{C_{{\rm{s}}}} \right]}}}} \right)$

Strong measurement - Change in the state of the system and the measuring device Weak measurement - "Not much" change in the state Strong measurement - Change in the state of the system and the measuring device Weak measurement - "Not much" change in the state What does that mean in SG?

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Image: A mathematical states and a mathem

• Weak inhomogeneous magnetic field

- Weak inhomogeneous magnetic field
- Keeping the screen close to the measuring apparatus

- Weak inhomogeneous magnetic field
- Keeping the screen close to the measuring apparatus

The final state of the system after measurement is still a mixture of both the spins.



Figure: Weak measurement followed by strong measurement and post selection. Source: Duck, Sudarshan, Phys.Rev.D (1989)

Post Selection

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Immediately after the weak measurement in one direction, we make a strong measurement in the direction perpendicular to both the direction of propagation and the direction weak measurement Immediately after the weak measurement in one direction, we make a strong measurement in the direction perpendicular to both the direction of propagation and the direction weak measurement Then we select one of the outputs hence selecting a definite final state for

the system

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Then we select one of the outputs hence selecting a definite final state for the system

Claim: If we start out with a spin 1/2 particle, after the above processes, we can end up with a spin 100 reading

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Definitions

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Observable that will be weakly measured: $\hat{A}\ket{a_n}=a_n\ket{a_n}$

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Observable that will be weakly measured: $\hat{A} |a_n\rangle = a_n |a_n\rangle$

Coupling of the measurement device to the observable: von Neumann model

 $\hat{H} = -g(t)\hat{q}\hat{A}$

where

- g(t) is a function with compact support near the time of measurement and normalised
- \hat{q} is the canonical variable of the measuring device and \hat{p} is its conjugate momentum

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Initial state of the system: $|\Psi_{in}\rangle = \sum_{n} \alpha_n |a_n\rangle$

Image: Image:

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Initial state of the system: $|\Psi_{in}\rangle = \sum_{n} \alpha_n |a_n\rangle$ Initial state of the measuring device: $|\Phi_{in}\rangle$

$$\begin{split} |\Phi_{in}\rangle &= \int dq \phi_{in}(q) |q\rangle \qquad (1) \\ |\Phi_{in}\rangle &= \int dp \widetilde{\phi}_{in}(p) |p\rangle \qquad (2) \end{split}$$

Initial state of the system: $|\Psi_{in}\rangle = \sum_{n} \alpha_n |a_n\rangle$ Initial state of the measuring device: $|\Phi_{in}\rangle$

$$|\Phi_{in}\rangle = \int dq \phi_{in}(q) |q\rangle$$
 (1)

$$|\Phi_{in}\rangle = \int dp \widetilde{\phi}_{in}(p) |p\rangle$$
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We will assume a gaussian spread in the p-representation centred at 0 with a spread $\Delta p = 1/(2\Delta) \Rightarrow \tilde{\phi}_{in}(p) = exp(-\Delta^2 p^2)$

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We will assume a gaussian spread in the p-representation centred at 0 with a spread $\Delta p = 1/(2\Delta) \Rightarrow \widetilde{\phi}_{in}(p) = exp(-\Delta^2 p^2)$ Hence $\Delta q = \Delta$ $\phi_{in}(q) = exp(-\frac{q^2}{4\Delta^2})$

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Evolution and Post Selection

Time evolution operator: $exp(-i \int \hat{H} dt)$

Assumption

During the time of measurement, the coupling Hamiltonian is assumed to dominate all other terms in the full Hamiltonian

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Time evolution of the system and the measuring device using this Hamiltonian and post selecting to obtain:

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Time evolution of the system and the measuring device using this Hamiltonian and post selecting to obtain: The final state of the device $|\Phi_f\rangle = \langle \Psi_f | exp(-i \int \hat{H} dt) | \Psi_{in} \rangle | \Phi_{in} \rangle$

Assumption

During the time of measurement, the coupling Hamiltonian is assumed to dominate all other terms in the full Hamiltonian

Time evolution of the system and the measuring device using this Hamiltonian and post selecting to obtain: The final state of the device $|\Phi_f\rangle = \langle \Psi_f | exp(-i \int \hat{H} dt) | \Psi_{in} \rangle | \Phi_{in} \rangle$ After some math:

$$|\Phi_f\rangle = \sum_n \alpha_n \alpha'_n \int dp exp(-\Delta^2 (p - a_n)^2) |p\rangle$$
(3)

A summation of gaussians centred at the eigenvalues of \hat{A}
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Define the weak value of A: $A_{w} = \frac{\langle \Psi_{f} | \hat{A} | \Psi_{in} \rangle}{\langle \Psi_{f} | \Psi_{in} \rangle}$

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$$= \langle \Psi_f | \Psi_{in} \rangle \left[1 + i q A_w + ... \right] | \Phi_{in} \rangle$$

Define the weak value of A: $A_{\mathbf{w}} = \frac{\langle \Psi_f | \hat{A} | \Psi_{in} \rangle}{\langle \Psi_f | \Psi_{in} \rangle}$ Hence $|\Phi_f \rangle = \langle \Psi_f | exp(iq\hat{A}) | \Psi_{in} \rangle | \Phi_{in} \rangle$

$$\begin{array}{l} \approx \langle \Psi_{f} | 1 + iq\hat{A} + ... | \Psi_{in} \rangle | \Phi_{in} \rangle \\ = \langle \Psi_{f} | \Psi_{in} \rangle \left[1 + iqA_{w} + ... \right] | \Phi_{in} \\ \approx \langle \Psi_{f} | \Psi_{in} \rangle \int dq e^{iqA_{w} - \frac{q^{2}}{4\Delta^{2}}} | q \rangle \end{array}$$

Define the weak value of A: $A_w = \frac{\langle \Psi_f | A | \Psi_{in} \rangle}{\langle \Psi_f | \Psi_{in} \rangle}$ Hence $|\Phi_f \rangle = \langle \Psi_f | exp(iq\hat{A}) | \Psi_{in} \rangle | \Phi_{in} \rangle$ $\approx \langle \Psi_f | 1 + iq\hat{A} + ... | \Psi_{in} \rangle | \Phi_{in} \rangle$ $= \langle \Psi_f | \Psi_{in} \rangle [1 + iqA_w + ...] | \Phi_{in} \rangle$ $\approx \langle \Psi_f | \Psi_{in} \rangle \int dq e^{iqA_w - \frac{q^2}{4\Delta^2}} | q \rangle$ Finally,

$$|\Phi_f\rangle \approx \langle \Psi_f |\Psi_{in}\rangle \int dp e^{-\Delta^2 (p-A_w)^2} |p\rangle$$
 (4)

A single gaussian centred at A_w !

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Hidden approximations!

- $|q^n \langle \Psi_f | \hat{A}^n | \Psi_{in} \rangle \parallel \ll |\langle \Psi_f | \Psi_{in} \rangle |, n \ge 2$
- $|q^n \langle \Psi_f | \hat{A^n} | \Psi_{in} \rangle | \ll |q \langle \Psi_f | \Psi_{in} \rangle |, n \ge 2$
- $|qA_w| \ll 1$

Hidden approximations!

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$$|q^n \langle \Psi_f | \hat{A^n} | \Psi_{in} \rangle || \ll | \langle \Psi_f | \Psi_{in} \rangle |, n \ge 2$$

- $|q^n \langle \Psi_f | \hat{A^n} | \Psi_{in} \rangle | \ll |q \langle \Psi_f | \Psi_{in} \rangle |, n \ge 2$
- $|qA_w| \ll 1$

But $q \leftrightarrow \Delta$. Hence

•
$$\Delta \ll \min_{n=2,3,\dots} \left| \frac{\langle \Psi_f | \hat{A} | \Psi_{in} \rangle}{\langle \Psi_f | \hat{A}^n | \Psi_{in} \rangle} \right|^{1/n-1}$$

• $\Delta \ll 1/A_w$

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Weak Value

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• Repeat the single particle experiment N times

- Repeat the single particle experiment N times
- Perform one measurement of an N particle ensemble

$$A_N = \frac{\Sigma A_i}{N}$$

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- Perform one measurement of an N particle ensemble

$$A_N = \frac{\Sigma A_i}{N}$$

will have (N+1) equally spaced eigenvalues.

Weak Value



Figure: Weak value of spin. Source: Vaidman "Weak Measurement" https://arxiv.org/abs/hep-th/9408154

Weak Value



Figure: Weak value of spin of N particles. Source: Vaidman "Weak Measurement" https://arxiv.org/abs/hep-th/9408154

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System: z-spin Probe: z-momentum System: z-spin Probe: z-momentum Hamiltonian: $\hat{H} = -\lambda g(t)\hat{z}\hat{\sigma}_z$

System: z-spin
Probe: z-momentum
Hamiltonian:
$$\hat{H} = -\lambda g(t)\hat{z}\hat{\sigma}_z$$

 $|\Psi_{in}\rangle = \frac{1}{\sqrt{2}} \begin{cases} \cos \alpha/2 + \sin \alpha/2 \\ \cos \alpha/2 - \sin \alpha/2 \end{cases}$

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Image: A matrix

System: z-spin
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 $|\Psi_f\rangle = \frac{1}{\sqrt{2}} \begin{cases} 1 \\ 1 \end{cases}$
Hence the weak value of spin is:
 $A_w = (\lambda \sigma_z)_w = \lambda \tan \alpha/2$

Image: Image:

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Playing with validity

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Condition to be valid for AAV's approximation: $\Delta \ll \lambda^{-1} \min[\tan \alpha/2, \cot \alpha/2]$

Condition to be valid for AAV's approximation: $\Delta \ll \lambda^{-1} \min[\tan \alpha/2, \cot \alpha/2]$ Hence α must not go too close to π but it can be taken arbitrarily close to π so as to measure a spin value of 100

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The Setup

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The Setup



Figure: Optical version of weak measurement (Source: Ritchie et al. Phys. Rev. Lett. (1990)

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First polarization:

$$\vec{E}_i = E_0 G(x) G(y) (\cos \alpha \hat{x} + \sin \alpha \hat{y})$$

where G(x) denotes gaussian in x centred at 0 with an FWHM of Δ

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- Angle made by the birefringent plate w.r.t. the y axis = θ
- Relative lateral displacement between o and e rays = $a = a(\theta)$
- Phase difference between o and e rays = ϕ

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Electric field now:

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- Angle made by the birefringent plate w.r.t. the y axis = θ
- Relative lateral displacement between o and e rays = $a = a(\theta)$
- $\bullet\,$ Phase difference between o and e rays = $\phi\,$

Electric field now:

$$\vec{E_w} = E_0 G(x) [\cos \alpha G(y+a) e^{i\phi} \hat{x} + \sin \alpha G(y) \hat{y}]$$
The Math

First polarization:

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Post selection by another polarizer:

The Math

First polarization:

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Electric field now:

$$\vec{E_w} = E_0 G(x) [\cos \alpha G(y+a)e^{i\phi} \hat{x} + \sin \alpha G(y) \hat{y}]$$

Post selection by another polarizer:

$$\vec{E_f} = E_0 G(x) [\cos \alpha \cos \beta G(y+a) e^{i\phi} + \sin \alpha \sin \beta G(y)] (\cos \beta \hat{x} + \sin \beta \hat{y})$$

The Math

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Image: Image:

$$I(y) = I_0[\cos^2 \alpha \cos^2 \beta G^2(y+a) + \sin^2 \alpha \sin^2 \beta G^2(y) + 2\cos \phi \cos \alpha \cos \beta \sin \alpha \sin \beta G(y)G(y+a)]$$

where I_0 is proportional to $|E_0|^2$

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where I_0 is proportional to $|E_0|^2$ Set $\alpha = \pi/4$

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where I_0 is proportional to $|E_0|^2$ Set $\alpha = \pi/4$

• $\beta=\alpha\Rightarrow$ constructive superposition; single, unshifted Gaussian

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where I_0 is proportional to $|E_0|^2$ Set $\alpha = \pi/4$

- $\beta = \alpha \Rightarrow$ constructive superposition; single, unshifted Gaussian
- $\beta = \alpha + \pi/2 + \epsilon$; $(\epsilon \ll 1) \Rightarrow$ destructive interference. Weak value $A_w \approx a \cot(\epsilon)/2$

Results

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Results



Figure: Intensity in the detector as a function of y when $a = 0.64 \mu m$ and $\Delta \approx 55 \mu m$ (Source: Ritchie et al. Phys. Rev. Lett. (1990))

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What we obtain by repeated measurement here is only the real value of A_w .

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Imaginary of A_w :

What we obtain by repeated measurement here is only the real value of A_w .

Imaginary of A_w :

- Shifts the momentum operator of the probe system.
- Determines the probability of post selection.

The imaginary component does not affect the weak value nor the average quantities.

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Observable: C Uncertainity in $Q = \Delta$

Image: Image:

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Observable: C Uncertainity in $Q=\Delta$ Perform the measurement N times and the standard deviation of $Q=\Delta/\sqrt{2}$ Signal to noise ratio

$$R = \frac{\langle Q \rangle_N}{\Delta_N} \tag{5}$$

Observable: C Uncertainity in $Q=\Delta$ Perform the measurement N times and the standard deviation of $Q=\Delta/\sqrt{2}$ Signal to noise ratio

$$R = \frac{\langle Q \rangle_N}{\Delta_N} \tag{5}$$

$$< Q>_N = N < Q> = Nc$$
 and $\Delta_N = \sqrt{N}\Delta$
Hence,

$$R = \sqrt{N} \frac{c}{\Delta} \tag{6}$$

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Let the system: $|\Psi\rangle \rightarrow |\Phi\rangle$ In the AAV regime, $c \ll \Delta$ and $\langle Q \rangle_{\Phi} = Re(C_w)$, hence Let the system: $|\Psi\rangle \rightarrow |\Phi\rangle$ In the AAV regime, $c \ll \Delta$ and $\langle Q \rangle_{\Phi} = Re(C_w)$, hence

$$R = \sqrt{N_{\Phi}} \frac{Re(C_w)}{\Delta} \tag{7}$$

Let the system: $|\Psi\rangle \rightarrow |\Phi\rangle$ In the AAV regime, $c << \Delta$ and $< Q >_{\Phi} = Re(C_w)$, hence

$$R = \sqrt{N_{\Phi}} \frac{Re(C_w)}{\Delta} \tag{7}$$

where $N_{\Phi} = N |\langle \Phi | \Psi \rangle|^2$

If measured in the P basis, according to Jozsa's paper, $< P >_{\Phi} = \Delta^{-2} Im(C_w)$ Standard deviation of P = $1/\sqrt{2}\Delta$ If measured in the P basis, according to Jozsa's paper, $< P >_{\Phi} = \Delta^{-2} Im(C_w)$ Standard deviation of P = $1/\sqrt{2}\Delta$ Hence the SNR is:

$$R = \sqrt{N_{\Phi}} \frac{Im(C_w)}{\Delta} \tag{8}$$

Hence if $Re(C_w) = Im(C_w)$ then R in both cases would be the same.

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What if the measuring device/probe is imperfect?

Now average the above w.r.t. Q_0 :

$$\overline{\langle Q \rangle_{\Phi}} = Re(C_w)$$

$$\overline{\langle Q^2 \rangle_{\Phi}} = \frac{\Delta^2}{2} + \frac{\Delta^2_Q}{2} + Re(C_w)^2$$
(10)

Now average the above w.r.t. Q_0 :

$$\overline{\langle Q \rangle_{\Phi}} = Re(C_w) \overline{\langle Q^2 \rangle_{\Phi}} = \frac{\Delta^2}{2} + \frac{\Delta^2_Q}{2} + Re(C_w)^2$$
(10)

Hence, SNR will have the same shift but with larger deviation.

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We consider a gaussian random variable in the P basis - P_0 with mean zero and deviation Δ_P we obtain:

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We consider a gaussian random variable in the P basis - P_0 with mean zero and deviation Δ_P we obtain:

But there is a twist in the tale!

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After weak measurement, the imaginary part of the weak value is responsible for the shift in momentum of the probe!

After weak measurement, the imaginary part of the weak value is responsible for the shift in momentum of the probe! Therefore, after weak measurement, the peak of P_0 distribution will be shifted by $\Delta_P^2 Im(C_w)$.

$$\overline{\langle P \rangle_{\Phi}} = (\Delta^{-2} + \Delta_P^2) Im(C_w)$$

$$\overline{\langle P^2 \rangle_{\Phi}} = \frac{\Delta^{-2}}{2} + \frac{\Delta_P^2}{2} + ((\Delta_P^2 + \Delta^{-2}) Im(C_w))^2$$
(12)

After weak measurement, the imaginary part of the weak value is responsible for the shift in momentum of the probe! Therefore, after weak measurement, the peak of P_0 distribution will be shifted by $\Delta_P^2 Im(C_w)$.

> $\frac{\overline{\langle P \rangle_{\Phi}}}{\langle P^{2} \rangle_{\Phi}} = (\Delta^{-2} + \Delta_{P}^{2}) Im(C_{w})$ $= \frac{\Delta^{-2}}{2} + \frac{\Delta_{P}^{2}}{2} + ((\Delta_{P}^{2} + \Delta^{-2}) Im(C_{w}))^{2}$ (12)

This yields an SNR,

$$R = \sqrt{N_{\Phi}} Im(C_w) \sqrt{\Delta^{-2} + \Delta_P^2}$$
(13)

After weak measurement, the imaginary part of the weak value is responsible for the shift in momentum of the probe! Therefore, after weak measurement, the peak of P_0 distribution will be

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(12)

This yields an SNR,

$$R = \sqrt{N_{\Phi}} Im(C_w) \sqrt{\Delta^{-2} + \Delta_P^2}$$
(13)

In this case, both the signal value and the deviation have changed.

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Mixed Probe State

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Time evolution operator: $U(\theta) = exp(-i\theta A \otimes K)$

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Time evolution operator: $U(\theta) = exp(-i\theta A \otimes K)$ Effectively, $U_{eff}(\theta) = exp(-i\theta A_w K)$

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Time evolution operator: $U(\theta) = exp(-i\theta A \otimes K)$ Effectively, $U_{eff}(\theta) = exp(-i\theta A_w K)$ Probe: $\sigma_i \rightarrow \sigma_f = P(f/i)U_{eff}(\theta)\sigma_i U_e ff^{\dagger}(\theta)$ Time evolution operator: $U(\theta) = exp(-i\theta A \otimes K)$ Effectively, $U_{eff}(\theta) = exp(-i\theta A_w K)$ Probe: $\sigma_i \rightarrow \sigma_f = P(f/i)U_{eff}(\theta)\sigma_i U_e ff^{\dagger}(\theta)$ Expectation value: $\langle M \rangle_{i/f} = \frac{tr(\sigma_{i/f}M)}{tr(\sigma_{i/f})}$

Time evolution operator:
$$U(\theta) = exp(-i\theta A \otimes K)$$

Effectively, $U_{eff}(\theta) = exp(-i\theta A_w K)$
Probe: $\sigma_i \rightarrow \sigma_f = P(f/i)U_{eff}(\theta)\sigma_i U_e ff^{\dagger}(\theta)$
Expectation value: $\langle M \rangle_{i/f} = \frac{tr(\sigma_{i/f}M)}{tr(\sigma_{i/f})}$
Shift operators: $\delta_{i/f}M = M - \langle M \rangle_{i/f}$

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$<\delta_{i}M>_{f}=i\theta Re(A_{w})<[K,M]>_{i}+\theta Im(A_{w})<\{\delta_{i}K,\delta_{i}M\}>_{i}+O(\theta^{2})$ (14)

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$$< \delta_i M >_f = i\theta Re(A_w) < [K, M] >_i + \theta Im(A_w) < \{\delta_i K, \delta_i M\} >_i + O(\theta^2)$$
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Put M = K, we get

$$<\delta_i K>_f = 2\theta Im(A_w) < (\delta_i K)^2 >_i + O(\theta^2)$$
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Image: A mathematical states of the state

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By measuring K, we obtain information regarding just the imaginary part of the weak value.

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SNR here is given by:

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$$R = \sqrt{N_{\Phi}} rac{Im(C_w)}{\Delta}$$
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Initial standard deviation of shift in K is maintained! Completely mixed state will have maximum standard deviation and hence the greatest SNR!



Figure: Setup for weak measurement with mixed probe states. Noise is introduced before and after probing. http://arxiv.org/abs/1211.4292v1

The result of the weak measurement is unaffected by the introduction of the phase noises.

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- Isignal to Noise Ratio
- 5 Mixed Probe State





Figure: http://arxiv.org/abs/1211.4292v1

Setup

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Initial state after the quartz plate: $|\psi_i\rangle = \frac{1}{\sqrt{2}}(|0\rangle + |1\rangle)$ where $|0\rangle$ and $|1\rangle$ are the upper and lower paths of light. Initial state after the quartz plate: $|\psi_i\rangle = \frac{1}{\sqrt{2}}(|0\rangle + |1\rangle)$ where $|0\rangle$ and $|1\rangle$ are the upper and lower paths of light. Post selection just before the QWP where the upper and lower paths interfere. Initial state after the quartz plate: $|\psi_i
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Then for the whole system,

$$U(\theta) = |0\rangle \langle 0| \otimes U_{HWP(\theta)} + |1\rangle \langle 1| \otimes U_{HWP(0)} = U_{HWP(0)}[|0\rangle \langle 0| \otimes exp(2i\theta Z) + |1\rangle \langle 1| \otimes I]$$
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Z is some observable that distinguishes the two circular polarizations. Hence the effective evolution is: $U(\theta) = exp(2i\theta P_0 Z)$ where P_0 is the projection (to $|0\rangle \langle 0|$) operator.
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This is experimentally obtained by plotting and finding the slope near $\theta=\mathbf{0}$

Visibility

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Image: A matrix

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Post selection is not complete, which affects the weak value. Actual post selected state: ρ_f In the case of no interaction: $\rho_f = V |\psi\rangle \langle \psi| + (1 - V)\frac{1}{2}$ where V is the visibility. Post selection is not complete, which affects the weak value. Actual post selected state: ρ_f In the case of no interaction: $\rho_f = V |\psi\rangle \langle \psi| + (1 - V)\frac{1}{2}$ where V is the visibility.

Hence the new weak value in terms of V:

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$$Vm(\langle P_0 \rangle_w) = \frac{V\sin\delta}{2(1+V\cos\delta)}$$
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when V = 1, we get back the original case.

Results



Figure: http://arxiv.org/abs/1211.4292v1

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Thank you!

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